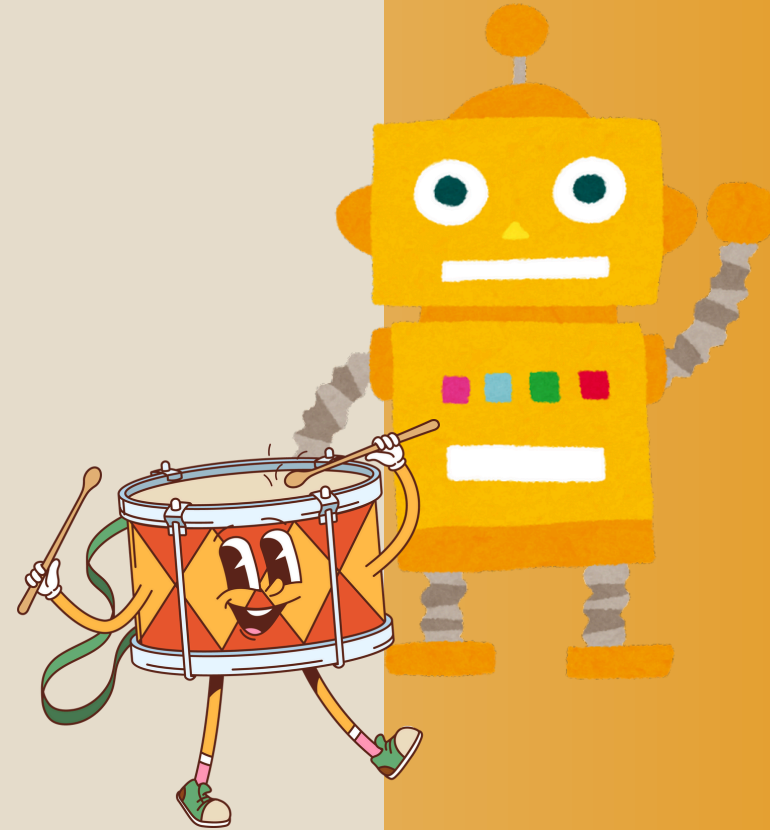


# ROBOKIDS

*Applied Project*



SEREN SARAC YILMAZ

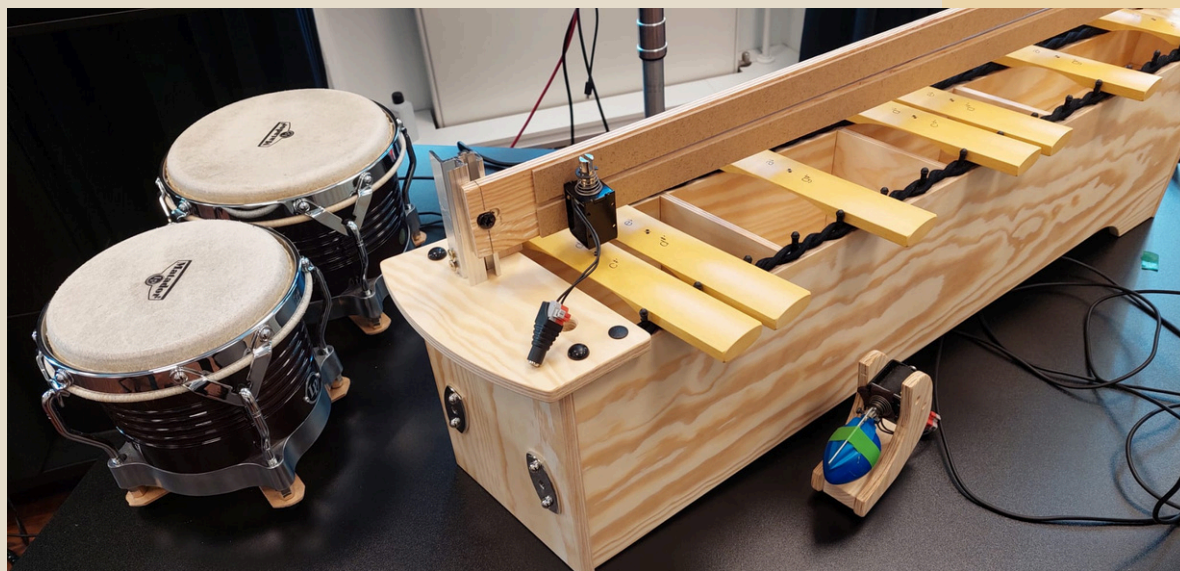
INTERDISCIPLINARY COLLOQUIUM III

## INTRODUCTION

- This presentation summarizes the current development stage of the Robo-Percussion project.
- Since the idea presentation, significant progress has been made in dataset creation, AI model training, and hardware preparation.
- The goal remains: AI-assisted musical co-creation for students and children.

## INSTALLATION







# DATA SET

Fachdidaktik EMP 2  
Hochschule für Musik Nürnberg

Emine Yaprak Kotzian

## SAR MAKARAYI

### Begleitmöglichkeiten

Grundton (3 Viertel)



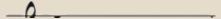
Grundton (Metrum)



Parallelschlag



Wechselschlag



Textrhythmus 1



Textrhythmus 2



Klangfarbe (Schlägelstile)



Glissando



Akzente



Spiel mit 3 Schlägeln



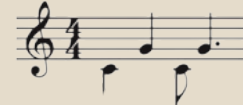
Wechselschlag



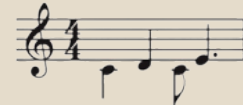
Bordun



Rhythmische Variation



Variation der Tonhöhe



Tremolo



Gegenbewegung



Eine bewegte Hand



Rhythmische Verschiebung



Tonleiter



Aufsteigend, zweistimmig



Klangfarbe (Holz)



Schlussmotiv



Link Ext Tap 120.00 4 / 4 1 Bar b# C Major 1. 1. 1 3. 1. 1 4. 0. 0 Key MIDI 44.1 kHz 0 %

Search (Cmd + F)

Collections

- Favorites
- Library
- All
- Sounds
- Drums
- Instruments
- Audio Effects
- MIDI Effects
- Modulators
- Plug-Ins
- Clips
- Samples
- Grooves
- Tunings

Content

- Type
- Sounds
- Drums
- Character
- Devices
- Function
- Name
- Tags: ROLI Add...

1 item selected

Groove Name Base Quantize Timing Random Velo

Swing 1... 1/16 0 % 100 % 0 %

Groove Pool Global Amount 0 %

1 MIDI 2 MIDI 3 Audio 4 Audio

Pattern10

MIDI From All Ins All Channels Monitor In Auto Off MIDI To No Output

Audio From Ext. In 1 2 Monitor In Auto Off Audio To Main

Sends A B

Drop Files and Devices Here

A Reverb B Delay Main

Cue Out 1/2 Main Out 1/2

Sends A B Post Post

Pattern10

Clip

Start Set End Set

1. 1. 1 2. 1. 1

Duplicate

Loop

Position Set Length Set

1. 1. 1 1. 0. 0

Signature Groove

4 / 4 None

Scale

C Major

Launch

Pitch & Time

C1 - F1 Fit to Scale Invert

0 sd Add Interval

Stretch

x2 /2

x1.0

Grid Set Length

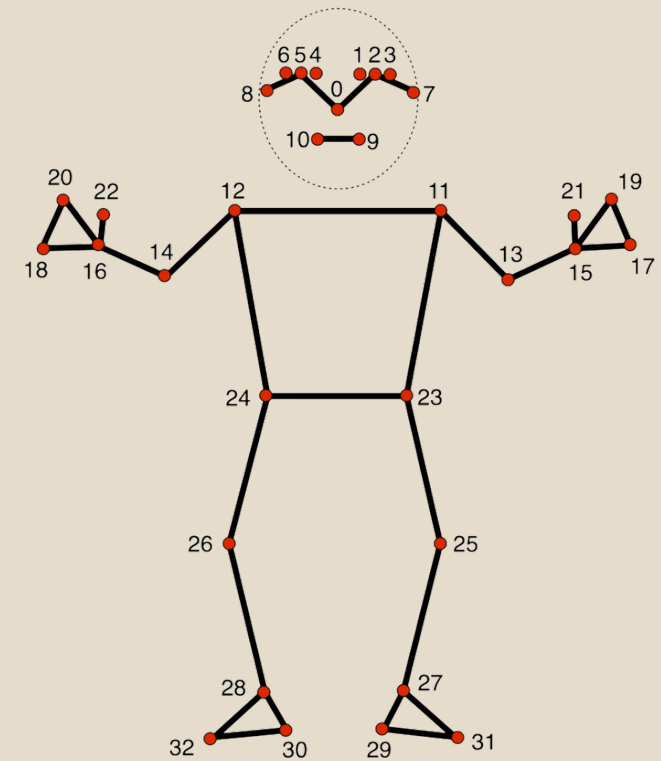
Velocity Randomize 100 Ramp 100 127

Downloading Live 12.3 - You'll be notified when the update is ready. [Click here for release notes.](#)

1-MIDI

6

## CODING MEDIAPIPE



Google AI. (n.d.). MediaPipe Pose Landmarker [Computer software].  
Retrieved December 2, 2025, from:  
[https://ai.google.dev/edge/mediapipe/solutions/vision/pose\\_landmarker](https://ai.google.dev/edge/mediapipe/solutions/vision/pose_landmarker)

Agents Editor

robopercussion\_controller.py

KIDS\_MUSIC\_CONTROLLER2.py LASTONE\_ROBOKIDS.py

Users > musicvan > Desktop > KidsMusicController-Package > LASTONE\_ROBOKIDS.py > ...

```
1  #!/usr/bin/env python3
2  """
3  Kids Music Controller - Orff Schulwerk Approach
4  Body movement control for educational music software
5  Perfect for children and music education installations
6  """
7
8  import cv2
9  import mediapipe as mp
10 import rtmidi
11 import time
12 import ssl
13 import math
14
15 # Fix SSL certificate issue
16 ssl_create_default_https_context = ssl_create_unverified_context
17
18 # ===== KID-FRIENDLY SETTINGS =====
19 MIDI_PORT = "IAC Bus 11 Bus 1"
20 MIDI_CHANNEL = 1
21
22 # Gesture detection settings
23 GESTURE_COOLDOWN = 0.15 # Slight delay for stability
24 GESTURE_THRESHOLD = 0.1 # Lower threshold for easier detection
25
26 # Continuous control settings
27 CONTINUOUS_CONTROL = True # Enable continuous control while in gesture pose
28 CONTROL_SENSITIVITY = 7.5 # Slightly faster response for clap
29
30 # Visual feedback colors (BGR format)
31 COLORS = {
32     'clap': (0, 255, 255), # Yellow
33     'wave': (0, 165, 255), # Orange
34     'default': (255, 255, 255) # White
35 }
36
37 # Smoothing and response settings
38 # - Lower smoothing = faster response, higher = smoother but slower
39 # - Max delta clamps how fast the CC can change per frame
40 SMOOTH_CLAP = 0.50 # Balanced smoothing for faster response
41 SMOOTH_WAVE = 0.55 # Balanced smoothing for faster response
42 MAX_DELTA_CLAP = 4 # Allow a bit faster knob catch-up
43 MAX_DELTA_WAVE = 4 # Allow a bit faster knob catch-up
```

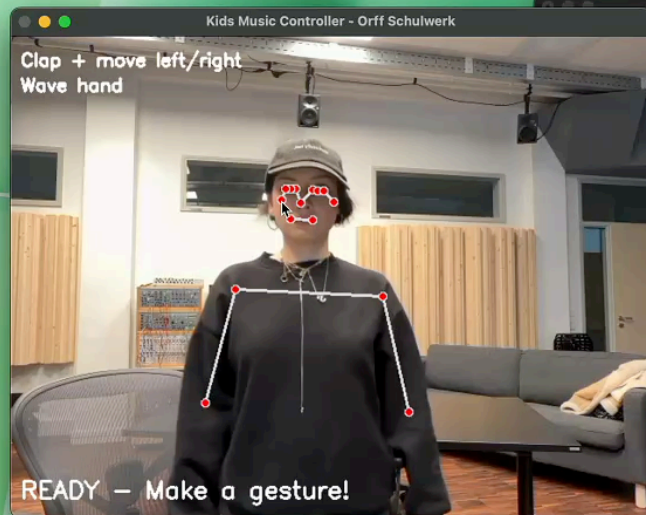
Review next file >

Cursor Tab Ln 1, Col 1









RoboKIDS

1 MIDI Xylophone Bongo + Shaker A Reverb B Delay Main

Pattern2 Pattern6 Pattern8 Pattern1 Pattern2 Pattern3 Pattern4 Pattern5 Pattern6 Pattern7

MIDI From All Ins All Channels Monitor In Auto Off MIDI To Xylophone Track In

Tags: Expression 1 Eintrag ausgewählt

pattern-vae-01

enable drive velThrsid offsetDrive Transpose

expand 64 65 1.00 36

NoModel model\_2025721\_135043

48 11

SaveModel loadModel

quick recall: loadRecentModel Model 1 Model 2 Model 3

loadModel InsertModel

0 Reset

ClearModelAndData

training Setup: Epochs: 1000 Batch Size: 12 Learning Rate: 0.00001

loadData Training

training status: epoch 1000, loss 73.32

MIDI Effect Rack

Key Vel Chain Hide C-2 C-1 C0 C1

Ziehen Sie MIDI-Effekte hierhin

Xylophone pattern-vae-01

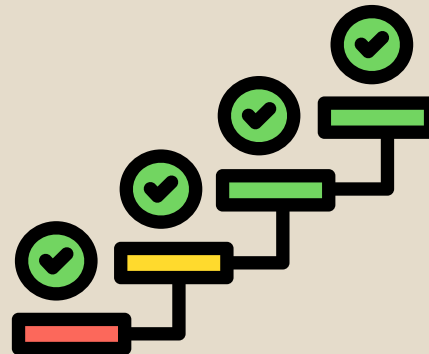


Bildschirmaufnahme 2025...40.mov



## NEXT STEPS

- Movements and melodies used in ORFF Schulwerk education will be added.
- Adjustments will be made in the code so that the rhythms stop when paused.
- Control in Ableton will be made closer to accurate.
- The workshop sequence will be designed from start to finish, and trials with students will begin around January.



**THANK YOU FOR  
LISTENING**

**SEREN SARAC YILMAZ**  
INTERDISCIPLINARY COLLOQUIUM